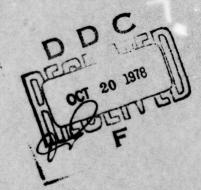


DATA BASE DEVELOPMENT FOR AIR FORCE SATELLITES Dennis E. Delorey

Dennis E. Delorey

SPACE DATE ANALYSIS LABORATORY **BOSTON COLLEGE** Chestnut Hill, Massachusetts 02167

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PREFACE

The author wishes to thank several members of the Space Data Analysis Laboratory for their efforts in relation to the tasks described in this report. Administrative assistance was provided by the Director of the laboratory, Mr. Leo F. Power, Jr. The analysis efforts of Mr. Paul N. Pruneau were, once again, commendable. Additional analysis support, programming and data base efforts were provided by Ms. Carolyn M. Parsons, Mr. Roger P. Vancour, Jr., Mr. Brian J. Donovan, Ms. Lisa Silva, Mr. Kenneth Dieter, Mr. Timothy Latson, Mr. Neil J. Grossbard and Mr. Brian F. Sullivan.

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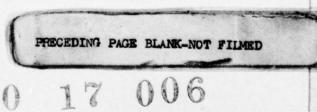


TABLE OF CONTENTS

Section		Page
	PREFACE	iii
	LIST OF ILLUSTRATIONS	ν
1.0	INTRODUCTION	1
2.0	S3 SATELLITES	2
	 2.1 Vehicle Operations and Spacecraft Telemetry 2.2 Data Processing Systems 2.3 S3-1 Data Base 2.4 S3-2 Experiments, Analysis and Software 	2 3 10 13
	2.4.1 Cold Cathode Ion Density Gauge 2.4.2 Mass Spectrometer (MSIV) 2.4.3 Piezoelectric Accelerometer 2.4.4 Fluxgate Magnetometer 2.4.5 Electrostatic Analyzer	15 16 18 19 21
3.0	SCATHA SATELLITE	24
	3.1 Overview 3.2 Telemetry 3.3 Agency Tapes	24 24 25
APPENDIX	A - B&L Format	27
APPENDIX	B - GSF Format	32
APPENDIX	C - Indices File Format	36
APPENDIX	D - MESA Data Base Format	38
APPENDIX	E - MSI Ion Data Base Format	43
APPENDIX	F - MSIV Ion Data Base Format	47
APPENDIX	G - Ion Density Gauge Data Base Format	52
APPENDIX	H - MSIV Neutral High Data Base Format	56
APPENDIX	I - S3-1 Data Base List (sample)	62

LIST OF ILLUSTRATIONS

Figure		Page
1	DPS - Phase I	5
2	DPS - Phase II	6
3	Geophysical Indices - S3-1 Lifetime	14

1.0 INTRODUCTION

The Space Data Analysis Laboratory (SDAL) of Boston College has been contracted by the Analysis and Simulation Branch (SUA) of the Air Force Geophysics Laboratory (AFGL) to develop mathematical and computer techniques necessary for the analysis of digital information from payloads flown aboard Air Force Satellites. The data analysis efforts require an integrated and systematic approach in order to incorporate the mathematical procedures associated with individual payloads while taking into account vehicle attitude and ephemeris parameters.

The prime efforts during the period covered by this report were associated with Satellites S3-1, S3-2, S3-3 and the SCATHA program.

In order to satisfy data analysis requirements, a data processing system (DPS) was developed and implemented for satellite S3-1. This system was adapted for use with the S3-2 and S3-3 vehicles. The system will be modified and adapted in order to satisfy requirements associated with the SCATHA program.

The S3-1 effort involved the creation of the final geophysical data bases for a Cold Cathode Ionization Density Gauge (IDG), the Miniature Electrostatic Accelerometer (MESA) and two mass spectrometers (MSI and MSIV). This effort entailed the completion of standard processing and the processing of data from problem orbits. Efforts were also expended on the selective processing of data from the Piezoelectric Accelerometer and from another ion density gauge. In addition, data compaction aimed toward the creation of a unified history file for this vehicle was of importance. Analysis efforts were involved in the development of software to integrate the appropriate data bases and produce history displays of selected parameters.

The S3-2 efforts dealt with the following experiments: Electrostatic Analyzer, Fluxgate Magnetometer, Piezoelectric Accelerometer, Cold Cathode Ionization Density Gauge and the MSIV mass spectrometer. The main emphasis was placed on the development of analysis to be used in the systematic processing of the data and the translation of the analysis into efficient computer software. Selected data has been processed for the probes mentioned. Creation and maintenance of the raw data files, the B&L files (magnetic and ephemeris data), Geophysical Support Files (neutral atmospheric model data)

and output module (OM) files (coefficients necessary for the computation of vehicle attitude) was an on-going effort.

For satellite S3-3, the principal responsibility of the SDAL lies in the development of the compacted raw data bases for the AFGL probes and the creation and maintenance of the B&L and OM files.

For the SCATHA project which is part of an Air Force program to investigate spacecraft charging at high altitudes, preliminary investigations were conducted into data analysis requirements in order to begin the adaptation of the S3 DPS for the SCATHA effort.

2.0 S3 SATELLITES

2.1 Vehicle Operations and Spacecraft Telemetry

The S3-1, S3-2 and S3-3 satellites were made of the same basic structural frame and the telemetry systems for all three vehicles were identical. Spacecraft operations for the three vehicles were, however, different.

The AFGL probes flown aboard the S3-1 vehicle were operated primarily during the perigee portion of orbits. This data was, in general, tape recorded and played back to Satellite Control Facility (SCF) remote tracking stations (RTS). Other operational modes allowed for the acquisition of full orbit and real time data but the perigee data was considered to be prime. For normal operations, data was recorded on every other orbit although increased coverage was obtained during periods of special interest, e.g., geomagnetic storms. Data from this vehicle was transmitted through approximately 2700 orbits.

The S3-2 spacecraft is still operational and has exceeded 10,000 orbits. The AFGL probes aboard the vehicle were categorized into two classes labeled Group I and Group II. The group I payloads were designed primarily for high latitude studies. The group II experiments were similar to probes flown aboard satellite S3-1 and, thus, the prime data was that of the perigee region. Vehicle operations allowed for the tape recording and playback of data from group I only, group II only or shared orbits in which data was acquired from both the group I and group II payloads. Real time acquisitions were also available for this vehicle.

The S3-3 satellite which is still operational obtains data over a longer orbital period than either of the other two S3 vehicles. The prime data for this vehicle is tape recorded and played back to SCF RTS. Real time data is also available for this vehicle.

As previously mentioned, the telemetry system used for all three vehicles was identical.

The satellite pulse code modulation (PCM) ata is telemetered to SCF remote tracking stations by Bi-Ø-L modulation of the carrier. The PCM data is transmitted at two data rates. Real time data is telemetered at 16,384 bits per second (bps). Tape recorder playbacks occur at 131,072 bps. Thus, the tape recorder playback to real time transmittal ratio is 8 to 1. Real time PCM data is transmitted by phase modulation in the reverse order from the real time data transmissions.

The satellite PCM systems consist of a 128 word main frame. Each data word is composed of eight bits and thus each main frame consists of 1,024 bits. Data is read out at a rate of 16 main frames per second with each main frame containing 24 subcom frames (sc) and five sub-subcom frames (ssc) in the sub frames. Thus a master frame (one read out from each word occurs over 256 main frames.

The processor provides an analog-to-digital converter which produces the eight bit digital values for all analog measurements providing an accuracy of \pm .2% \pm 1/2 LSB. Included in this figure are all error contributions from the processor input, at sampling time, to the processor output. The voltage range for encoding is 0 to 5.12 VDC.

The PCM processor generates the satellite time word (STW). The STW consists of 28 bits and allows for an accumulation through 194 days. The four least significant bits of the STW serve as a subcom identifier while least significant bits 5 through 8 identify the sub-subcom frame. The synchronization pattern is contained in main frame words 126, 127 and 128.

2.2 Data Processing Systems

Due to the volume of data to be processed, the complexity of the processing requirements and the necessity of taking a systematic approach to the data processing task, a data processing system (DPS) was developed and implemented for S3-1. The DPS allowed for maximum data flow, flexibility of implementation and adaptability to future vehicles. In fact, the S3-1 DPS was generalized for use with the S3-2 and S3-3 spacecrafts. The program interfaces and general data flow are identical in the DPS for all three vehicles although versions of some programs exist for each spacecraft.

In order to understand the effort involved in the creation of the geophysical unit data bases and unified history file, a brief description of the data processing system is now presented. The processing may be thought of as occurring in two phases. Figure 1 is a flow diagram of Phase I of the DPS while Figure 2 represents the Phase II program interfaces. For vehicles S3-1 and S3-2, both phases are implemented. For satellite S3-3, only Phase I is required.

In Phase I, all files to be input into the individual experiment data processing routines are created. These files consist of the raw experiment data files, magnetic parameter and ephemeris files, atmospheric model files and files containing the coefficients to be used in determining vehicle attitude. In Phase II, the individual experiment processing routines are executed and geophysical unit data bases for each spacecraft revolution are created. For satellite S3-1, in addition to these geophysical unit data bases, a unified history file containing reduced data from all probes is to be created. Through history file usage, reduced geophysical unit correlations may be made for all probes which are simultaneously studying the same atmospheric phenomena. Moreover, the unified history file results in compaction of the data to one flexible file.

The PCM data transmitted from the vehicle is recorded on tape at various SCF remote tracking stations. These tapes are, in turn, sent to the Space and Missile Test Center (SAMTEC) for digitization and storage onto 9 track tape.

The file name used by SAMTEC for this digital data is the Standard Telemetry Format (STF). The STF for each orbit consists of a file descriptor record (FDR), data index records (DIR), data index continuation records (DIC), data records (DR), end of data records (ED) and end of real records (ER).

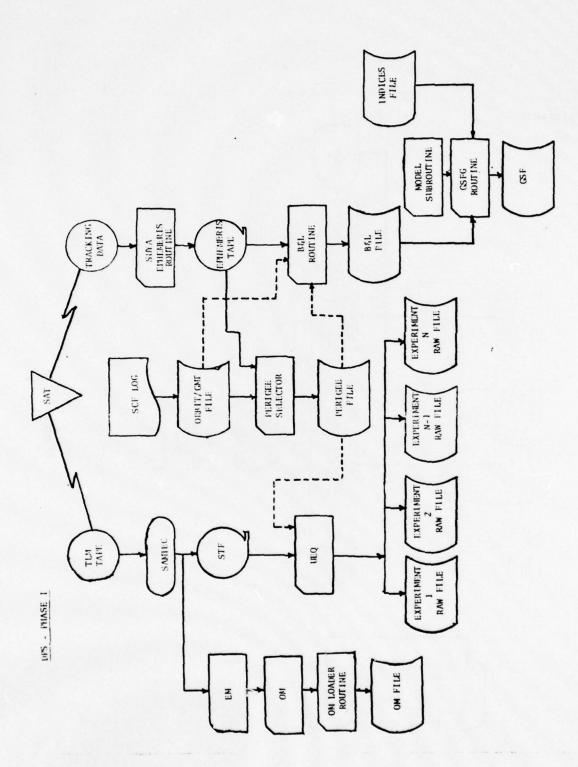


Figure 1



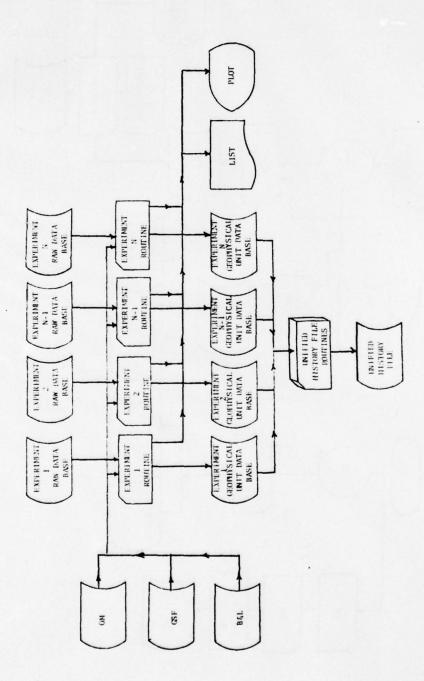


Figure 2

The FDR contains parameters related to the particular orbit on the STF tape. such as, analog tape number, date of orbit and date of digitization. and DIC records exist for the purpose of defining word locations within DR's for both clock correlation factors and all word designations from the telemetry data. Data records for the telemetry data always begin with subcom frame 1, but the first data frame on each STF tape is random relative to the sub sub-com frame. Sync and spare words are deleted in the digitization process. Thus, in general, the DIR and DIC information will not be consistent from one STF tape to another. The ED records signal the end of information for the time correlation and telemetry information for each STF tape. ER is the signal for end of reel operations. The set of data products received at AFGL/SUA for each orbit processed through the SAMTEC digitization system is the STF tape, its associated scan listing and a deck of cards for attitude determination. The scan listing contains orbit number, start and stop times of the digitized signal and satellite time words (STW) at which digital dropout occurred. The card deck, generated in conjunction with the STF creation, results from a computer routine called the Estimation Module (EM). The cards contain sets of coefficients to be used in the computation of vehicle attitude.

Another item used in the DPS is the Satellite Control Facility tape recorder log. Copies of this log are also received by AFGL/SUA.

With these items provided by sources external to AFGL, the first phase of the DPS is ready for implementation.

A card image file of the SCF tape recorder log, called the Orbit/GMT file, is created. This file contains the orbit number, date and start and stop times of each tape recorder orbit. For S3-1 and Group II operations for S3-2, prime data occurred for the AFGL probes in the perigee region of each orbit but satellite turn-on normally occurred prior to an extending beyond the perigee region. In order to determine the areas of each pass containing the prime data, a computer routine was written to input the orbit/GMT file and to interrogate ephemeris files. Outputs from the perigee selector routine consist of the orbit number, date and start and stop time of the perigee sections. These parameters are stored on a file which can be displayed but which is also used as input to routines written to construct

the experiment raw data files and their associated model and magnetic parameter files. The use of the perigee information file plays a key role in data compaction for the B&L and GSF files for S3-1 and S3-2 Group II operations. The orbit/GMT file plays a similar role for S3-2 Group I data as well as the S3-3 data.

When the STF, scan listing and EM deck are received at AFGL/SUA, the tape number and pertinent orbit information are entered into a cross-reference log, the scan listing is filed and the card deck, called the output module (OM), is prepared for loading onto a monthly OM file. Since the SAMTEC digitization process is not done chronologically by orbit number, the systematic approach taken in the storage of these cards is to create one file for each month of vehicle lifetime. A cross-reference listing of file and orbit number is produced whenever OM data is added to any file.

Since the STF contains data from the full PCM data stream, a computer routine was written to create raw data files for each experiment. This routine is called the unpack/edit/quality check (UEQ) routine. This routine uses as input the STF tape and pertinent information from the perigee file, if applicable, such as the prime data area. Perigee file usage is required only on S3-1 and S3-2. The UEQ then extracts all necessary information from the FDR, DIR and DIC; unpacks data records according to DIR and DIC specifications; quality checks time code information and sub-com frame numbers; determines occurrences of signal loss; edits out bad data frames; calculates GMT from the STW information; performs averages of specific designations as necessary; and creates a raw data file for each experiment in a format which optimizes data storage and retrieval. Permanent storage of output files is, of necessity, accomplished through the use of off-line devices. A version of the UEQ exists for each of the S3 vehicles.

The SCF sends tracking data to AFGL/SUA and this data is, in turn, used by SUA to produce ephemeris files. These files created by SUA cover periods of one month at a time with data provided in 1 minute intervals. Parameters contained on the SUA ephemeris file include altitude, longitude, geocentric and geodetic latitude, vehicle velocity in component form and local time. Since the data on the file covers a full one month period, it can be compacted by selecting out only the areas for which telemetry data was acquired.

Since all processing routines for the individual probes require ephemeris as well as magnetic parameters, the ephemeris compaction and combination ephemeris and magnetic file (B&L file) is created in the next step of the processing system. An existing routine was modified for use with these satellites. The modified routine, called the B&L program, uses as input the monthly ephemeris file and the pertinent parameters from the perigee file (or orbit/GMT file) to create a B&L file for the prime data of each orbit. One B&L tape is created for each month of the lifetime of the satellites. Among the quantities stored on the B&L file for each orbit are all pertinent ephemeris parameters, magnetic field components, total field, L-Shell and geomagnetic longitude, latitude and local time. Data occurs at 60 second increments for each pass. A modular subroutine was written for the extraction of any or all of the quantities on the B&L file at any time during an orbit. Versions of the B&L routine exist for each of the three satellites.

An INDICES file was created for the lifetime of satellite S3-1 and is being maintained and updated for S3-2 and S3-3. This file contains all geophysical indices necessary for the interpretation of geophysical unit measurements and for the calculation of model atmospheric parameters. Among the parameters contained on this file are Kp, $F_{10.7}$ CM solar flux, Ap, DST index, calcium plage indices, solar flare indices and solar declination. A modular routine, GPARAM, was written to interrogate this file and to allow for the determination of any of the above quantities for any orbit during the lifetime of a vehicle.

Most of the AFGL probes flown aboard S3-1 and the Group II probes from S3-2 perform neutral atmospheric measurements. The processing requirements for these probes include the knowledge of selected atmospheric neutral model parameters. To this end, the Geophysical Support File (GSF) is created. The GSF contains parameters such as exospheric temperature, temperature at altitude, mass density and number density for various constituents. The routine used to create the GSF is called the GSFC and it uses an SUA supplied subroutine to perform the actual model computations. Inputs to the GSFC are the B&L file and the INDICES file. Thus, the GSF are created on a one tape per month basis with file and orbit numbers matching those of the B&L file.

File formats for the B&L, GSF and INDICES file are included in the appendix.

Programs to be executed in the second phase of the DPS require raw data files, B&L files, OM files and in some cases GSF files.

Software developed in both phases of the DPS was written in modular fashion in order that multi-purpose routines could be used wherever elements of commonality exist in the processing requirements.

The processing routines developed for Phase II of the DPS create the geophysical unit data bases. These routines also create listings and displays of the geophysical unit parameters along with selected.

2.3 S3-1 Data Base

As mentioned in the introduction, the data bases for the probes flown aboard this spacecraft have been nearly completed. The addition of data from a small percentage of problem orbits will complete these data bases. A brief description of each of the S3-1 probes for which data bases were created is included in this section.

Satellite deceleration due to aerodynamic drag was measured by the MESA accelerometer and from the aerodynamic drag, neutral atmospheric density was derived. The sensing element of the instrument consists of an electrostatically suspended proof mass which is electrostatically force rebalanced along its sensitive axis. A digital output which represents the pulse rate and which is proportional to the applied acceleration is obtained from the restoring voltages. The probe is capable of operating in two sensitivity ranges. Range A provides low sensitivity measurements. The normal operational mode for the instrument was range B.

The MSI is an RF quadrupole mass spectrometer designed to provide atmospheric species measurements between 14 and 44 amu. Density measurements for 0, 0_2 , N_2 , NO and A_r were obtained. The experiment was not synchronized to the PCM encoder and the instrument output was therefore free running with respect to the data stream. Probe operation consisted of two modes, each of approximately 12 seconds duration. One 12-second mode consisted of four

scans of masses from 14 through 44 amu. While in the second mode, only N_2 , (28 amu) was examined.

The main output for the Cold Cathode Ionization Density Gauge is gauge current which was sampled at 16 points per second. The gauge current values were modulated by satellite spin with the maximum amplitude of the signal occurring at the minimum attack angle (the angle between the instrument's look angle and the velocity vector). The instrument was designed to provide atmospheric neutral density measurements and spatial and temporal variations.

The MSIV instrument was composed of an RF quadrupole mass spectrometer and a velocity mass spectrometer to measure atmospheric composition and species density of masses between 1 and 44 amu. The instrument was designed for operation in five different modes with mode switching occurring only by command to the spacecraft. Operation of the instrument was synchronized to the PCM encoder for each of the five modes. The spectra measurement from the instrument was a 24 bit digital output. Through the various modes, outputs were provided for ion, neutral high and neutral retarded measurements.

The processing and analysis techniques (including functional flow diagrams) used in the creation of the data bases for the individual probes were included in a previous report (AFGL-TR-76-0121, Delorey).

The general structure of the data base for each probe is the same. By keeping all files of the same general form, data retrieval and display can be effected through the use of multi-purpose routines. Data from each orbit is contained on a physical file consisting of a header record followed by data records which include the appropriate geophysical unit measurements and selected positional parameters. Information stored in both the header and data records is structured by frame. Two integer count words precede the information in each physical record. These count words represent the number of words in a data frame and the number of data frames in the record.

The MESA data base contains atmospheric neutral density measurements along with GMT, selected ephemeris and magnetic parameters and model density. Data is contained in the file for each orbit at two rates. One data set yields 2 density measurements per vehicle spin cycle (vehicle spin rate was 5 ± 1 rpm). The other data set contains measurements in 2 km increments. The header record

for each orbit contains standard information such as acquisition orbit number, date of orbit, and data taking interval but coefficients to least squares polynomial fits are also included. Density measurements were fit as functions of altitude for the downleg and upleg portions of each orbit.

The MSI data base, which has been completed, follows the same general structure defined above. The header record contains standard information pertinent to the particular orbit. The data records provide density measurements (in number density) for selected constituents and the corresponding positional parameters. The data rate is one frame per 12 second scan mode. This converts to approximately one data set every other vehicle spin cycle. Computer software was developed in order to fit and hence compact the downleg and upleg data sets for each constituent. The fits were performed to number density as a function of altitude.

The Cold Cathode Ionization Density gauge data base is constructed in a manner analagous to the MESA data base. The data records include gauge pressure, ambient pressure, atmospheric neutral density and selected model, ephemeris and magnetic parameters. Data storage occurs at a rate of one frame per vehicle spin cycle. Fitting techniques were applied to the downleg and upleg portions of the density data. The coefficients, from which density versus altitude may be computed, are stored in the header record.

The main data bases created for the MSIV instrument were for the prime operational mode of the experiment-mode 1. In this mode, both ion and neutral high measurements were performed. Thus, there are two data bases for the MSIV; one for ions and one for neutral highs. The header records for each contain standard orbit related parameters such as date of acquisition, orbit number and GMT of the acquisition. The data records for the ion data base contain currents for masses 14, 16, 28, 30 and 32 in addition to selected magnetic and ephemeris parameters. These currents are readily convertable into number density. The data records in the neutral high data base were created in a manner analagous to the ions. These records contain currents for masses 14, 16, 28, 30 and 32. The data rate at which storage occurred for both data bases was one frame per vehicle spin cycle. Computer

software has been developed for the fitting of the upleg and downleg portions of each orbit with the resultant coefficients having density versus altitude applications.

The data bases for the individual probes are used to study structure within individual orbits and to perform analyses on small or large segments of the data. The creation of these data bases has yielded a tremendous compaction of the data. Approximately 1500 STF tapes were originally received and the geophysical unit data bases for all probes now reside on approximately 15 tapes. Thus, the compaction ratio is 100:1. A data base list routine was developed whereby selected parameters relevant to each acquisition and the file location for each probe within the data base are displayed. The geophysical index Kp is also displayed on the listing. A sample of the data base printout and the formats for the individual data bases are included in the appendix.

The concept of the unified history file was developed to provide a flexible data base from which studies of long term effects could be performed. This data base which is presently being put into final form will contain coefficients to fits which will allow the computation of geophysical unit parameters from each of the individual data bases. Note that these coefficients already exist in the header records of each orbit for the MESA and ion density gauge. Further, as already mentioned, software was developed to produce the coefficients for the mass spectrometers. Similar techniques were employed to produce coefficients for selected model parameters. Thus, the coefficients can be used to obtain geophysical unit or model data. Ephemeris and magnetic parameters are also selectable from the unified history file. The geophysical indices associated with each orbit are also retrievable. A display of the geophysical indices over the lifetime of the vehicle is included as Figure 3. The indices are displayes as a function of date. Displays have been created for some of the probes reflecting mass density at fixed altitude with additional grids for Kp, F_{10.7} CM solar flux and latitude and local time of perigee. Additional constraints can easily be placed on data selection to, for instance, extract only orbits which fall into specific Kp ranges. The coefficients are the key element in extracting the geophysical unit measurements. One further advantageous feature of the unified history file

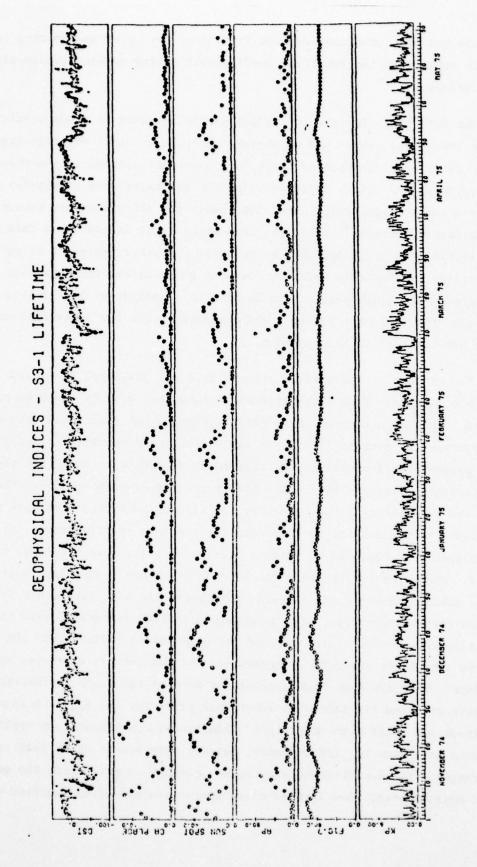


Figure 3

is that of data compaction. It is estimated that, when in final form, this entire file will be contained on one tape. Thus, the final data compaction ratio from STF to unified history file will be 1500:1.

2.4 S3-2 Experiments, Analysis and Software

For the S3-2 spacecraft which is still in orbit, geophysical unit data bases are being developed for the Fluxgate Magnetometer, Electrostatic Analyzer, MSIV and Cold Cathode Density Gauge (IDG). The data for the Piezoelectric accelerometer is selectively processed.

Data base development implies the continuance of UEQ executions and the creation of B&L, GSF, OM and indices files in a systematic manner.

This section contains a brief description of each experiment and the analysis and computer software which were developed.

2.4.1 Cold Cathode Ion Density Gauge

The S3-2 cold cathode ion density gauge flown was designed to provide atmospheric neutral density measurements and spatial and temporal variations. Basically, the output signal from the probe is modulated by the spin of the vehicle with the maximum response occurring when the angle between the intrument and the satellite velocity vector is at a minimum. Gauge current is the direct measurement of the instrument. The current is converted to pressure and then, through analysis techniques analagous to those developed for S3-1, atmospheric neutral density is computed.

Instrument readouts and data rates are summarized below:

Gauge Current	16 pps
Range Indicator	16 pps
High Voltage	1 pps
Electronics Temperature	.0625 pps
Gauge Temperature	.0625 pps

Due to the higher perigee of this vehicle, as compared to S3-1, many of the anlysis techniques developed for S3-1 required tailoring for application to this spacecraft. The basic instrument readouts were quite similar to those of S3-1.

The functional flow of data through the main processing routine is summarized below.

The frames of raw telemetry data are input through the use of a modular input routine. Instrument range, gauge current and gauge pressure are then calculated on a point-for-point basis. Instrument attack angles are then calculated for all pressure values through the OM module and OM file. The data is then separated into the decreasing and increasing attack angle portions of the ram cycle. The instrument sampling function, R (S,D,α) , is computed. Gauge pressure is fit as a function of the R (S,D,α) for the separated portions of the spin cycle. The data fitting is accomplished through a modular polynomial routine. Slopes of the fitted curves are extracted and corrected pressures are calculated for the into and out of ram portions of the satellite rotation and these pressures are then averaged and atmospheric neutral density is computed. All necessary ephemeris parameters are then extracted from the B&L file and atmospheric neutral density is calculated. Selected model atmospheric parameters are extracted from the Geophysical Support File. These parameters include mass density, pressure and temperature at altitude.

Each program execution results in the creation of listings, plots and the data base. The parameters listed and plotted are quite similar to those resulting from S3-1 program exeuctions. The data base for each orbit consists of a header record and data records contain the computed geophysical unit, ephemeris, magnetic and model parameters.

2.4.2 Mass Spectrometer (MSIV)

The mass spectrometer flown aboard the S3-2 satellite was similar to the MSIV flown on satellite S3-1. The probe was made up of an RF quadrupole mass spectrometer in combination with a velocity mass spectrometer. The probe was designed to measure atmospheric composition and species density. Species studied were between 1 and 44 amu with both neutral and ion measurements of 0, N_2 , NO, N_1 , H and H_2 provided. The operation of this MSIV experiment was synchronized to the PCM encoder and five commandable modes of operation were possible. The prime output from the probe was a 24 bit digital readout. Instrument readouts and associated data rates are summarized below:

It is possible that the gain values (G) in Table VI will be modified after some of the data is reduced and spectral radiance features in each of the four gain channels are compared.

24 bit digital spectra	64 pps
RF Monitor	64 pps
Beam (EMR) Monitor	4 pps
Pressure Monitor	8 pps
Ratio (V _R) Monitor	8 pps
DC Monitor	8 pps
Commutator	1 pps
Mode Monitor	1 pps
High Voltage (HV) Monitor	2 pps

The probe could be operated in 5 modes. Mode 1 was capable of providing a combination of neutral high (NH) and ion measurements or be operated in an ions only mode. Mode 2 provided a combination of neutral high and neutral retarded measurements. In mode 3, the data set consisted of NH only. Mode 4 and mode 5 were primarily diagnostic.

For all modes, the RF monitor indicated the mass being sampled. The 24 bit digital spectra output contained a range bit and the number of counts measured by the multiplier. A maximum of two output ranges was possible. A one readout lag was programmed between the RF monitor and the spectra output (the spectra lagged the RF monitor by one readout) but the lag sporadically extended to 2 readouts. The experiment timing cycle was 1 second for modes 1, 2 and 3; 2 seconds for mode 4 and 8 seconds for mode 5. In modes 1, 2 and 3 there were four readouts for each mass, thus producing a peak shape. Several monitors were also included as instrument outputs.

The main emphasis has been placed on the processing of the mode 1 data. In this mode, the instrument can be commanded to perform ion/neutral high or ion data only measurements. The mode monitor voltage is used to discern the measurement type. In ion only mode, data processing and analysis are performed on masses 14, 30, 28, 16, 1 and 4. In the ion/NH mode, ion measurements are performed on masses 14, 30, 28 and 16 while neutral high masses examined are 1, 4, 7, 14, 30, 28 and 16.

The functional flow of data through the mode 1 routine may be summarized as follows. The instrument mode is determined first. Then, the instrument

range is extracted and the corresponding multiplier counts converted to current. Attack angles corresponding to the currents are computed using the OM module.

For ion data, the peaks are translated to ram using a function dependent only on attack angle and the four seconds of data closest to ram are scanned and one group of ion readouts is selected for analysis based on criteria involving current amplitude. Ratio monitor (R_A) data associated with ion readouts is converted to current and translated to ram. Magnetic pitch angle is calculated and pertinent positional parameters such as longitude, geodetic and geomagnetic latitude, local time and magnetic field are computed from information contained on the B&L file. A number of ratios involving individual currents, summed currents and the R_A are then computed.

For neutral high data, statistical techniques are employed in the data selection. The four readouts around each mass peak are examined, and after removing the two extrema, the remaining points are averaged. This procedure is employed for each mass in the four frames of data closest to ram. Once an average current value is obtained for each mass in those four frames, the currents are translated to ram by use of the neutral high sampling function. Statistical checks are then performed and one current for each mass is selected.

Each program execution results in plots, listings and data base storage. The plots and listings of the reduced geophysical unit parameters and associated magnetic and ephemeris information are similar to the S3-1 outputs. The data bases for both the ion and neutral high values are created in a structure similar to the S3-1 files.

2.4.3 Piezoelectric Accelerometer

The triaxial piezoelectric accelerometer flown aboard the spacecraft provides atmosphere neutral density measurements. Satellite deceleration, due to aerodynamic drag, is measured along the three mutually orthogonal axes. Instrument outputs are analog signals (OV to 5V) with readouts for three sensitivity levels along each axis. The telemetry words and data rates are summarized below:

X-axis	range	3	4 pps
X-axis	range	2	1 pps
X-axis	range	1	1 pps
Y-axis	range	3	1 pps
Y-axis	range	2	1 pps
Y-axis	range	1	1 pps
Z-axis	range	3	1 pps
Z-axis	range	2	1 pps
Z-axis	range	1	1 pps
Tempe	rature		.0625 pps

The processing of data from this probe is done selectively. Mathematical and computer techniques developed for the reduction and analysis of accelerometer data from previous spacecrafts were adapted and modified for use with S3-2 piezoelectric accelerometer.

Filtering techniques are required in the processing of this accelerometer data. The computer routine filters the signal in order to determine the portion of data due to atmospheric drag. A power spectral analysis of the data revealed the existence of two and sometimes three peaks. A numerical notch filter was designed to remove the extraneous signal. Once filtered, atmospheric neutral density measurements are computed. Plots and listings of the mass density measurements as functions of GMT and other ephemeris, magnetic and model atmosphere parameters are output by the routine.

2.4.4 Fluxgate Magnetometer

The fluxgate magnetometers flown aboard the S3-2 spacecraft were designed to measure the 3 components of magnetic field to a resolution of 5 γ . The full scale range for each axis (0V \rightarrow 5V) corresponds to $\pm 600 \ \gamma$ (.02V corresponds to 4.8 γ).

Each axis has a neutralizing winding current of 10 ma/gauss so that a known biasing field may be applied (to each axis) to keep the magnetometers on scale.

When the voltage level of a fluxgate axis reaches 0.1 or 4.9V the range switch provides current increments of 0.1 ma to the neutralizing coil (0.1 ma corresponds to 1000 y). These current increments, applied in the proper

direction, keep the magnetometer from saturating. There are 128 different current levels available to each axis which correspond to steps of 1000 γ ranging from -64000 γ to +63000 γ . The current being applied to any axis is determined by the range switching coarse and fine outputs for that axis. For the coarse outputs, there are eight telemetry levels from 0 + 5V in steps of 0.71V (seven steps). For fine outputs, there are 16 levels between 0 + 5V. The 15 steps are in increments of .-3V. The zero current step for coarse is at 2.84V and for fine is at 0V. The current steps for each axis vary from -64 to +63 and the step level may be determined by the expression

$$16N + M$$

where

N,M are integers determined by

$$N \simeq \frac{\text{coarse volts - 2.84}}{.71}$$

$$M = \frac{\text{fine volts}}{.33}$$

Saturation levels for any range switch axis are determined by a coarse-fine voltage pair of (0.0,0.0) or (5.0,5.0).

Instrument outputs and associated data rates are as follows:

X-magnetometer	32 pps
Y-magnetometer	32 pps
Z-magnetometer	32 pps
X-axis range switch-fine	16 pps
Y-axis range switch-fine	16 pps
Z-axis range switch-fine	16 pps
X-axis range switch-coarse	2 pps
Y-axis range switch-coarse	2 pps
Z-axis range switch-coarse	2 pps
Sensor temperature	1 pps
Electronics temperature	1 pps
Range switch temperature	1 pps

All outputs are analog. The data for this payload is processed in two phases due to the high sensitivity of the instruments; differing readout rates for the fine, coarse and magnetometer designations; and the uncertainty of the alignment for the boom mounted sensor axes.

The first phase, called the preprocessing, is performed in order to create a data base of raw magnetometer readings (in gammas). Corrections for erratic fine and coarse readouts are performed in this routine. A more detailed description of the analysis efforts involved in the preprocessing is contained in a previous report (AFGL-TR-77-0103, Delorey). Plots, listings, and the raw magnetic field data base result from each execution of the preprocess routine.

The final processor uses the raw magnetometer data base and B&L files as input. Data is processed only in areas where the absolute value of the latitude exceeds 45° . The steps performed in this routine include the following:

- Digital filtering of the x, y and z magnetic field measurements to produce smoothed signals.
- ii) Computation of a correction to the η_2 angle (caused by the twisting of the boom-mounted sensor axes). This angular correction is not constant for each orbit and is, thus, expressed as a function of time.
- iii) Calculate model magnetic field components and total field in the spacecraft coordinate frame of reference.
- iv) Transform the spacecraft principal axis measurements into the coordinate frame of reference used to express the model field parameters.
- v) In the model field coordinate system, difference the measured and model x,y,z and total field.
- vi) Compute an average curve from the x-axis data (principal axis system) at the extrema values of the signal and subtract from this curve the transformed y model field component.

- vii) Plot and list the computed parameters along with associated ephemeris and magnetic information.
- viii) Create a final data base in the same generalized structure as for other S3 probes.

2.4.5 Electrostatic Analyzer

The S3-2 electrostatic analyzer was designed to perform a 32 channel differential energy analysis of electrons between approximately 1 kev and 16 kev by means of electric field deflection through a parallel plate system. A channeltron electron multiplier is used to detect the selected electrons which are counted in a 10 bit binary counter with an additional overflow bit indicator. An inflight calibration source and test pulse generator are included within the instrument to assure the accumulation of one count during each data interval.

A 5 bit up/down counter programs the deflection voltage in a 64 step sequence. The counter steps from 00000₂ to 11111₂ then back to 00000 in 64 steps. The 10 bit data counters, 1 bit overflow indicator and 5 bit up/down control counter are read out as a single 16 bit word at the uniform rate of 64 samples/second. The five bit control counter is incremented every other readout; therefore, a complete 64 step sequence (32 up, 32 down) is completed every 2 seconds.

There are 10 analog monitors which provide outputs used to ascertain proper instrument performance. Monitors 26-11-9 and 26-11-10 will assume different levels for each energy channel.

For the overflow bit, the normal value is 1. An overflow is indicated by a $0\ \text{value}$.

Instrument outputs and associated data rates are as follows:

ESA output (16 bit digital)	64
+5v monitor	2
+15v monitor	2
-5v monitor	2
+10v reference monitor	4
+28v monitor	1

Temperature monitor	1
+3kv monitor	8
+3kv input current monitor	8
-10kv input current monitor	8
-10kv reference input monitor	8

Computer software has been developed to create an ESA data base and to perform analyses upon the data base. This processing occurs in two phases.

In the first phase, science data is produced and a data base is created for later use in the analysis phase. The basic functions of this software may be summarized as follows:

The 16 bit digital readout is decoded and the accumulated counts are extracted; the readouts are ordered into 2 second data frames; areas of digitization dropout are dummy filled and flagged in order to maintain a consistent file structure; magnetic and ephemeris parameters are merged; average energy, average flux and total flux are computed on a sweep by sweep basis; plots listings and the data base are created. For each orbit, the listings are broken down into three sections: GMT and the raw counts readout by the instrument with areas of data dropout flagged; the housekeeping monitors converted to voltage and one minute averages of the monitors; GMT, magnetic pitch angle, average energy, average flux and total flux. Displays generated by the routine are segmented to produce one set of plots for each hemisphere. Each set of plots represents average energy, average flux, total flux and magnetic pitch angle as functions of GMT. Additional axes yield annotation for altitude, geodetic latitude, longitude, magnetic local time, invariant latitude and geomagnetic latitude. The data base consists of a header record followed by data records structured to allow easy input to analysis routines. Data records contain GMT, ephemeris and magnetic parameters and counts. The counts are always stored such that energy level 00000, begins the frame.

Two analysis routines have been written to access the ESA data base; the first produces displays of spectra (flux versus energy) for individual sweeps while the second routine is used to sort data into selectable bins and perform averages and statistical evaluations.

The basic functions of the second routine may be summarized as follows: the data from the data base is input to the routine and the orbit is immediately separated into the sunlight and shaded portions since the data is to be treated separately for the two cases; the data is then sorted into predefined latitude bins with starting, ending and incremental values optional; for each latitude bin, the counts are converted to flux and the flux values are sorted into energy bins of optional width; for each energy level, the average flux and statistical error is computed; flux data is sorted into predefined magnetic pitch angle bins (of optional width) for each energy bin and average flux statistical error and average energy are computed; finally, for each magnetic pitch angle bin, average energy, total energy flux and total flux are computed. Formulae used in this routine were detailed in a previous report (AFGL-TR-77-0103, Delorey).

3.0 SCATHA SATELLITE

In this section, an overview of the SCATHA project, telemetry systems and agency file concepts are discussed.

3.1 Overview

The P78-2 spacecraft is part of an Air Force project to investigate Space Charging at High Altitude (SCATHA). The vehicle will be launched into a near synchronous orbit. On-orbit data will be controlled by the Satellite Control Facility and its remote tracking stations. The duration of the mission is scheduled for 12 months.

The vehicle is scheduled for launch from the Eastern Test Range in 1979. The space vehicle (SV) will initially be placed in a circular parking orbit from which it will be placed into a transfer orbit at the first ascending node. At apogee after 3 1/2 revolutions in the transfer orbit, the vehicle will be placed into its near synchronous final orbit with a 2.5 degree inclination. The approximate apogee and perigee in final orbit are 23100 nmi and 15038 nmi, respectively. This orbit will result in a nominal longitudinal drift of 6 degrees per day. The orbital orientation is such that the vehicle will experience a sequence of altitudes near synchronous altitude at local midnight during the vernal eclipse season.

The vehicle is expected to acquire up to 24 hours of data per day for the 1 year period. The payloads to be flown aboard the vehicle were designed to provide data related to charging, discharging and plasma interaction phenomenae. In particular, investigations will be made on different particle types and energy ranges; magnetic field intensities of both the environment and those generated by the SV; the effects of charging and discharging on spacecraft materials; the interaction of the charging and discharging phenomenae with SV operation and the techniques for controlling the SV charge condition.

3.2 Telemetry

The P78-2 telemetry system provides for the transmission of PCM and PM data. There are two primary encoders, an auxiliary encoder and two tape recorders aboard the vehicle.

The characteristics of the primary encoder may be summarized as follows:

128 words/mainframe
8 bits/word
1024 bits/mainframe
8 mainframes/seconds
8192 bits/second
128 mainframes/masterframe
16 seconds/masterframe.

The auxiliary encoder may be characterized in summary form as follows:

64 words/mainframe
8 bits/word
512 bits/mainframe
1 mainframe/second
512 bits/second
4 mainframes/masterframe
4 seconds/masterframe.

The broadband analog data from the vehicle will provide high rate information for several experiments. Five modes were defined for broadband operations but only one mode may be operated at any time.

3.3 Agency Tapes

A new concept, called the agency tape (AT), will be used by SAMTEC in the digitization of data for the SCATHA satellite. This new type of file replaces the STF used for the S3-1, S3-2 and S3-3 satellites. The actual file structure has resulted from meetings between SUA, SDAL and SAMTEC personnel. Rather than digitizing the entire PCM mainframe, an agency tape is created for each experiment which contains only the specific designations requested. Each orbit on the AT will have at least four types of records; header record, scan record, event record and telemetry records. The header record contains information specific to the vehicle and orbit such as orbit number, date of orbit, GMT at the start and end of the pass. The scan record will contain information pertaining to areas of digitization dropout. The event record is specific to each agency tape type. It may contain information from the telemetry stream obtained in the first pass of the 2 pass SAMTEC system.

The telemetry records contain GMT and the digital values for the specified designations.

One of the preliminary efforts of the SDAL with respect to this vehicle has been to aid the SUA analysts in defining agency tape information. From the overview section it is seen that coverage of up to 24 hours per day may be expected. Thus, it is obvious that efficient storage of the PCM data into the data records is imperative. The structure which was defined results in significant data compaction yet allows for compatibility with S3 system techniques.

It is suggested that each record contain masterframes of data with each masterframe starting at the mainframe containing subcommutator frame 0. By storing masterframes, as opposed to mainframes, on each physical record, a maximum of information may be stored on each magnetic tape. Further, by storing each masterframe in a consistent manner (starting at subcommutator level zero), the necessity of having individual processing routines search each file to find word locations of subcommutated data is removed. This will help in minimizing the computer coding in these routines. The more important factor, however, is data storage. Estimates were made using the preliminary telemetry lists from two of the AFGL probes aboard the vehicle and these estimates were used to conclude that a full day (24 hours) of data could be stored on each agency tape.

APPENDIX A

B%L FILE FORMAT

B&L-File Header Record

0.1	Word Count	
0.2	Group Count (1)	
1	Satellite name	A
2	Modified Julian date at start of pass	F
3	Month of year at start of pass	F
4	Day of month at start of pass	F
5	Year (last two digits of 19xx)	F
6,7	Coefficients used in mag. field calculations	A
8	Epoch year of coefficients	F
9	Date coefficients initially updated to	F
10	Start time of pass (GMT) seconds	F
11	End time of pass (GMT) seconds	F
12	Time increment (seconds)	F
13	<pre>Indicator for magfield package 0. = INVAR/FIELDG, 1. = SHELLG/FELDG</pre>	F
14	Error value for INVAR	F
15	Semi-major axis (km)	F
16	Eccentricity	F
17	Inclination	F
18	Right ascension of ascending mode	F
19	Argument of perigee	F
20	Time of perigee (GMT) sec - neg + N/A	F
21	Altitude of perigee (km)	F

B&L-File Header Record (Cont.)

22	Longitude of perigee (+E)
23	Latitude of Perigee (geodetic)
24	Local time of perigee - seconds
25	Time of apogee (neg → no apogee)
26	Altitude of apogee (km)
27	Longitude of apogee (+E)
28	Latitude of apogee (geodetic)
29	Local time of apogee ~ seconds
30	Start time of vehicle in $sun_1 (neg \rightarrow N/A)$
31	End time of vehicle in sun_1 (neg \rightarrow N/A)
32	Start time of vehicle in shade $(neg \rightarrow N/A)$
33	End time of vehicle in shade $(neg \rightarrow N/A)$
34	Start time of vehicle in sun_2 (neg \rightarrow N/A)
35	End time of vehicle in sun_2 (neg \rightarrow N/A)
36	Start time of vehicle in shade $_2$ (neg \rightarrow N/A)
37	End time of vehicle in shade $(neg \rightarrow N/A)$
38	Longitude at start of pass
39	Longitude at end of pass
40	Latitude (geodetic) at start of pass
41	Latitude (geodetic) at end of pass
42	Altitude at start of pass
43	Altitude at end of pass
44	Rev no.
45-50	Vacant

B&L - File Data Records

0.1 Word count 0.2 Group count 1 Modified Julian Date 2 Calendar month 3 Calendar day 4 Calendar year 5 Hour of day Minute of hour 7 Second of minute 8 GMT in seconds x coordinate of position vector (km) 9 10 y coordinate of position vector (km) 11 z coordinate of position vector (km) 12 x coordinate of velocity vector (km/sec) y coordinate of velocity vector (km/sec) 13 14 z coordinate of velocity vector (km/sec) 15 Satellite altitude (km) 16 Distance of satellite from center of earth (km) Satellite velocity (km/sec) 17 18 Geocentric latitude (±90°) 19 Geodetic latitude (±90°) 20 Satellite longitude (+E) 21 Geomagnetic local time (seconds) 22 Local time (seconds)

B&L - File Data Records (Cont.)

23	x coordinate of magnetic field (geodetic) in gamma's
24	y coordinate of magnetic field (geodetic) in gamma's
25	z coordinate of magnetic field (geodetic) in gamma's
26	Geomagnetic coordinate - B
27	Geomagnetic coordinate - L
28	Geomagnetic latitude
29	Geomagnetic longitude
30	Magnetic inclination
31	Magnetic declination
32	Invariant latitude
33	Corrected geomagnetic latitude
34	Corrected geomagnetic longitude
35	Local corrected magnetic time
36	Solar zenith angle
37	Solar longitude
38	Solar right ascension
39	Solar declination
40	Mean anomaly
41-50	Vacant

APPENDIX B
GSF FILE FORMAT

(GSF) Geophysical Support File Header Record

CDC	FORMAT	DESCRIPTION
0.1	I	Word count
0.2	I	Group count
1	Α	Satellite name
2	F	Modified Julian date
3	F	Month of year at start of pass
4	F	Day of month at start of pass
5	F	Year of month at start of pass
6	F	Time at start of pass-GMT (Sec)
7	F	Time at end of pass-GMT (Sec)
8	F	Time increment
9	F	Semi Major axis at start of pass
10	F	Eccentricity at start of pass
11	F	Inclination at start of pass
12	F	Right ascension of ascending node
13	F	Argument of perigee
14	F	Time of perigee-GMT Sec (neg \rightarrow N/A)
15	F	Altitude of perigee (km)
16	F	Longitude of perigee (+E)
17	F	Latitude (geodetic) of perigee
18	F	Local time of perigee (Sec)
19	F	Time of apogee-GMT Sec (neg \rightarrow N/A)
20	F	Altitude of apogee (km)
21	F	Longitude of apogee (+E)

(GSF) Geophysical Support File Header Record (Cont.)

CDC	FORMAT	DESCRIPTION
22	F	Latitude of apogee (geodetic)
23	F	Local time of apogee (sec)
24	F	Start time of vehicle in $sun_1 (neg \rightarrow N/A)$
25	F	End time of vehicle in $sun_1 (neg \rightarrow N/A)$
26	F	Start time of vehicle in shade $(neg \rightarrow N/A)$
27	F	End time of vehicle in shade $(neg \rightarrow N/A)$
28	F	Start time of vehicle in $sun_2(neg \rightarrow N/A)$
29	F	End time of vehicle in sun_2 (neg \Rightarrow N/A)
30	F	Start time of vehicle in shade $(neg \rightarrow N/A)$
31	F	End time of vehicle in shade $(neg \rightarrow N/A)$
32	F	F10.7 cm solar flux $(F_{10.7})$
33	F	F (3 month average)
34	F	K _p value
35	F	A _p value
36	F	Longitude (+E) at start of pass
37	F	Longitude (+E) at end of pass
38	F	Latitude (geodetic) at start of pass
39	F	Latitude (geodetic) at end of pass
40	F	Altitude at start of pass
41	F	Altitude at end of pass
42	F	Rev no. (f)
43-50	F	Vacant

APPENDIX C

INDICES FILE FORMAT

Indices File Format

WORD NO.	FORMAT	DESCRIPTION
1	F	Month of year
2	F	Day of month
3	F	Year (last 2 digits of 19xx)
4-11	F	K _p values (8)
12	F	F _{10.7} cm solar flux
13	F	Solar declination
14	F	Ap
15	F	Relative sunspot number
16	F	Daily solar index
17	F	Calcium plage
18-41	F	Hourly D _{st} index

APPENDIX D

MESA ACCELEROMETER DATA BASE

MESA Accelerometer Data Base

Header Record:

```
No. of words in header record (45)
0.1
0.2
            Integer (1)
            Satellite Name
  1
  2
            Month of year at start of pass
  3
            Day of month at start of pass
  4
            Year (last 2 digits of 19xx)
  5
            Time at start of pass (GMT sec)
            Time at end of pass (GMT sec)
  7
            Time of perigee (GMT sec)
  8
            Altitude at perigee (km)
            Geocentric longitude at perigee (Degrees, +E)
  9
 10
            Geodetic latitude at perigee
 11
            Local time of perigee (sec)
 12
            Start time of vehicle in sun (neg N/A)
 13
            End time of vehicle in sun (neg N/A)
 14
            Start time of vehicle in shade (neg N/A)
 15
            End time of vehicle in shade (neg N/A)
 16
            Start time of vehicle in sun2 (neg N/A)
 17
            End time of vehicle in sun2 (neg N/A)
            Start time of vehicle in shade<sub>2</sub> (neg N/A)
 18
 19
            End time of vehicle in shade2 (neg N/A)
 20
            F<sub>10.7</sub> cm solar flux
            F (3 month average)
 21
 22
            K_{p}
 23
            Orbit Number
 24
            a_0
 25
                       Downleg data coefficients to fit
            aı
 26
            a2
                              15 + \log p = \sum_{i=0}^{4} \mathbf{a}_{i} \mathbf{z}^{i}
 27
            a<sub>3</sub>
 28
                                 = density, z - altitude
```

MESA Accelerometer Data Base

29	b ₀	
30	b ₁	Upleg data - coefficients to fit
31	b ₂	4 ;
32	b3	$15 + \log \rho = \sum_{i=0}^{4} b_i z^i$
33	b ₄	1-0
34	т1	
35	c_1	Constants used in bias correcting data
36	Т2	
37	т2	
38	1	
39		
40		
41		Vacant
42		
43		
44		
45		

MESA Accelerometer Output Data Base - Data Records Output values are for ram points only

0.1	Number of words in a group (20)
0.2	Number of groups in a logical record (25)
1	Time (GMT seconds)
2	Altitude
3	Geodetic latitude
4	Geocentric longitude
5	Geomagnetic latitude
6	Geomagnetic longitude
7	Local time (sec)
8	Drag
9	ρ calculated
10	ρ model
11	Ratio (ρ meas/ρ model)
12	Attack Angle
13	L-Shell
14	Orbit normal angle
15	Temperature and bias corrected counts
16	Drag coefficient
17	Geocentric latitude
18	Vacant
19	Vacant
20	Vacant

The ram point outputs for the full pass comprise the first part of the MESA data base.

The second part of the data base is made up of points from the curve fit in 2 km intervals between 250 km and perigee. Perigee point is added.

The two portions of the file are separated by IND = 1, JGRP - 1, DATA = 0.0.

For the fitted data

0.1 Word Count (10) Group Count (50) 0.2 1 GMT 2 ALT 3 Geodetic latitude Geocentric longitude 5 Geomagnetic latitude Geomagnetic longitude 6 7 ρ (from fit) 8 ρ model 9 Rat io 10 Local time

APPENDIX E

MSI DATA BASE

MSI Data Base - Header Record

0.1 Word Count (20) 0.2 Group Count (1) 1 Experiment (MSI) 2 Orbit Number 3 Month of Year Day of month of orbit 5 Year (last two digits of 19xx) 6 Start time of orbit (GMT-sec) 7 End time of orbit (GMT-sec) Start time of vehicle in sun-GMT sec (<0+N/A) 9 End time of vehicle in sun-GMT sec (<0+N/A) 10 Start time of vehicle in shade - GMT sec (<0+N/A) End time of vehicle in shade - GMT sec (<0+N/A)11 12 R (average R for orbit) 13 GMT (sec) of perigee 14 Altitude (km) of perigee 15 Longitude (+E) of perigee 16 Latitude of perigee 17 Local time of perigee (sec) 18 T (average sphere temp for orbit) 19 Vacant 20 Vacant

MSI Data Base Data Records

```
0.1
           Word Count (50)
           Group Count (10)
0.2
           Time (GMT sec) ram
  1
  2
           Altitude (km)
  3
           Geodetic latitude
  4
           Longitude
  5
           Invariant latitude
  6
           L-shell
  7
           Geomagnetic latitude
  8
           Magnetic local time (sec)
  9
           Velocity (km/sec)
           I<sub>14</sub> (current for mass 14)
 10
           \alpha_{14} (attack angle of current for amu 14; + into ram, - out
 11
                      of ram)
           116
 12
 13
           α<sub>16</sub>
           I<sub>18</sub>
 14
 15
           α<sub>18</sub>
 16
           128
 17
           α<sub>28</sub>
 18
           I<sub>30</sub>
 19
           α<sub>30</sub>
           132
 20
 21
           α<sub>32</sub>
 22
           I 34
           \alpha_{34}
 23
 24
           140
 25
           a40
```

MSI Data Base - Data Records (Cont.)

```
26
              144
27
              α4
              N<sub>16</sub>
28
29
              N<sub>28</sub>
              N<sub>40</sub>
30
              N<sub>14</sub>
31
              N_T (N_T + \Sigma N_i)
32
              \rho \ (\rho = k \Sigma N_i M_i)
33
              Time (sit mode 70^{\circ} into ram) (T_{+70})
34
35
              Altitude
              \alpha at T_{+70}
36
              I<sub>28+70</sub>
37
              N<sub>28+70</sub>
38
              Time (sit - ram) (T<sub>R</sub>)
39
              Alt at TR
40
              \alpha at T_R
41
              I<sub>28</sub> ram
42
43
              Time (sit mode - 70^{\circ} out of ram) (T_{-70})
44
              Alt at T-70
45
              \alpha at T_{-70}
46
              I<sub>28-70</sub>
47
48
              N<sub>28-70</sub>
49
              Vacant
50
              Vacant
```

APPENDIX F
MSIV ION DATA BASE

MSIV Ion Data Base Header Record

0.1	Word Count (23)
0.2	Group Count (1)
1	Experiment (MSIV)
2	Orbit Number
3	Month of year of orbit
4	Day of month of orbit
5	Year (last 2 digits of 19xx)
6	Start time of orbit (GMT-sec)
7	End time of orbit (GMT-sec)
8	Start time of vehicle in sun $(<0\rightarrow N/A)$
9	End time of vehicle in sun $(<0\rightarrow N/A)$
10	Start time of vehicle in shade $(<0\rightarrow N/A)$
11	End time of vehicle in shade $(<0\rightarrow N/A)$
12	GMT of perigee (sec)
13	Altitude of perigee (km)
14	Longitude (+E) of perigee
15	Geodetic latitude of perigee
16	Geomagnetic latitude of perigee
17	Invariant latitude of perigee
18	Local time of perigee
19	Magnetic local time of perigee
20	Corrected magnetic local time of perigee
21	Commutator ₁
22	Commutator ₂
23	Commutator ₃ from first 8 frames
24	Commutator ₄ of data in pass
25	Commutators
26	Commutator ₆
27	Commutator ₇
28	Commutators

MSIV Ion Data Base Header Record (Cont.)

29	Commutator ₁	
30	Commutator ₂	
31	Commutator3	
32	Commutator4	From last 8 frames
33	Commutator ₅	of data in pass
34	Commutator ₆	
35	Commutator ₇	
36	Commutators	
37	Vacant	
38	Vacant	

MSIV Ion Data Base Data Records

```
0.1
          Word Count (39)
0.2
            Group Count (13)
  1
           Time of start of selected frame (GMT seconds)
  2
            Altitude (km)
  3
            Geodetic latitude
  4
            Geomagnetic latitude
  5
            Invariant latitude
            L-Shell
  6
  7
            Longitude (+E)
  8
            Magnetic local time (sec)
  9
            Corrected magnetic local time (sec)
 10
            Local time (sec)
            I<sub>14</sub> (corrected to ram)
 11
            I<sub>16</sub> (corrected to ram)
 12
 13
            I<sub>28</sub> (corrected to ram)
            I<sub>30</sub> (corrected to ram)
 14
            I 32 (corrected to ram)
 15
            \alpha_{14} at time of I_{14} (\alpha = attack angle)
 16
 17
            \alpha_{16} at time of I_{16}
 18
            \alpha_{28} at time of I_{28}
            \alpha_{30}^{} at time of \mathbf{I}_{30}^{}
 19
            \alpha_{32} at time of I _{32}
 20
            \beta_{14} at time of I_{14} (\beta = pitch angle)
 21
            \beta_{16} at time of I_{16}
 22
           \beta_{28} at time of I_{28}
 23
            \beta_{30} at time of \mathbf{I}_{30}
 24
            \beta_{32} at time of I_{32}
 25
```

MSIV Ion Data Base Data Records (Cont.)

```
\Sigma I_{i} (where I_{i} are corrected currents)
26
           {\sf RA}_1 (where RA has been translated to ram)
27
28
           \alpha_{RA_1}
           RA_2 (translated to ram)
29
           \alpha_{RA_2}
30
            RA_3 (translated to ram)
31
           \alpha_{\text{RA}\,3}
32
           TI_1
33
           TI_2
34
           TI3
35
           TI_4
36
            Beam Monitor<sub>1</sub>
37
            Beam Monitor_2
38
39
            High Voltage Monitor
```

APPENDIX G

ION DENSITY GAUGE DATA BASE

Data Base Storage: Ion Density Gauge

Header Record

- 0.1 Word Count (35)
 0.2 Group Count (1)
 - 1 Orbit No.
 - 2 Month of orbit
 - 3 Day of orbit
 - 4 Year of orbit (last two digits of 19xx)
 - 5 K_p for orbit
 - 6 F_{10.7} cm flux for orbit
 - 7 Start time of orbit (GMT sec)
 - 8 End time of orbit (GMT sec)
 - 9 Start time of vehicle in sun
- 10 End time of vehicle in sun
- 11 Start time of vehicle in shade
- 12 End time of vehicle in shade
- 13 Perigee time (GMT sec)
- 14 Perigee altitude (km)
- 15 Perigee longitude (+E)
- 16 Perigee latitude
- 17 Local time of perigee (sec)
- 18 Electronics temperature (average)
- 19 Gauge temperature (representative value)
- 20 TGE (calculated Tg)

Data Base Storage: Ion Density Gauge (Cont.)

Data Records - Ion Density Gauge Data Base

- 0.1 Word Count (21)
- 0.2 Group Count (24)
 - 1 Time (ram) (GMT sec)
 - 2 Altitude (km)
 - 3 Longitude (+E)
 - 4 Latitude (Geodetic)
 - 5 Magnetic latitude
 - 6 Local time (seconds)
 - 7 I (current at 40° going into ram)
 - 8 Pg (pressure at 40° going into ram)
 - 9 R (S, D, α) (R factor at 40° going into ram)
- 10 I (current at 40° going out of ram)
- 11 Pg (pressure at 40° going out of ram)
- 12 R (S, D, α) (R factor at 40° out of ram)
- 13 Pressure into ram (from fit)
- 14 Pressure out of ram (from fit)
- 15 Average pressure (average of 13, 14 above)
- 16 Measured density ρ
- 17 Model density (J '71)
- 18 Model temperature (J '71)
- 19 Model pressure (J '71)
- 20 High Voltage
- 21 Vacant

Words 1-21 repeat 23 times

APPENDIX H MSIV NEUTRAL HIGH DATA BASE

MSIV Neutral High (NH)

Header Record

0.1	Word Count (38)
0.2	Group Count (1)
1	Experiment (MSIV - NH)
2	Orbit Number
3	Month of year of orbit
4	Day of month of orbit
5	Year (last two digits of 19xx)
6	Start time of orbit (GMT sec)
7	End time of orbit (GMT sec)
8	Start time of vehicle in sun ($<0 = >N/A$)
9	End time of vehicle in sun ($<0 = >N/A$)
10	Start time of vehilce in shade $(<0 = >N/A)$
11	End time of vehicle in shade ($<0 = >N/A$)
12	GMT of perigee (sec)
13	Altitude of perigee (km)
14	Longitude (+E) of perigee
15	Geodetic latitude of perigee
16	Geomagnetic latitude of perigee
17	Invariant latitude of perigee
18	Local time of perigee
19	Magnetic local time of perigee
20	Corrected magnetic local time of perigee

MSIV Neutral High (NH) (Cont.)

21	Commutator 1		
22	Commutator 2		
23	Commutator 3		
24	Commutator 4	}	From first 8 frames of data in
25	Commutator 5		the pass
26	Commutator 6		
27	Commutator 7		
28	Commutator 8)	
29	Commutator 1)	
30	Commutator 2		
31	Commutator 3		
32	Commutator 4	}	From last 8 frames of data in
33	Commutator 5		the pass
34	Commutator 6		
35	Commutator 7		
36	Commutator 8)	
37	Vacant		

Data Records - MSIV Neutral High Data Base

0.1	Word Count (72)
0.2	Group Count) (≤7)
1	GMT at point closest to ram (sec)
2	Altitude
3	Geodetic
4	Longitude (+E)
5	Invariant latitude
6	L-shell
7	Geomagnetic latitude
8	Magnetic local time
9	Corrected magnetic local time
10	Velocity (km/sec)
11	Pitch Angle
12	T_1 ram
13	T ₁ ram
14	T ₁ wake
15	I ₁ wake
16	T ₂ ram
17	I ₂ ram
18	T ₂ wake
19	I ₂ wake
20	T ₄ ram
21	I4 ram
22	T ₄ wake
23	I4 wake
24	T ₁₄ ram
25	I ₁₄ ram
26	T ₁₄ wake
27	I ₁₄ wake
28	T ₁₆ ram
29	I ₁₆ ram
30	T ₁₆ wake
31	I ₁₆ wake

Data Records - MSIV Neutral High Data Base (Cont.)

```
32
                T28 ram
33
                I28 ram
34
                T<sub>28</sub> wake
35
                I28 wake
36
                T<sub>30</sub> ram
37
                I30 ram
38
                T<sub>30</sub> wake
39
                 I30 wake
40
                T<sub>32</sub> ram
41
                 I32 ram
42
                T<sub>32</sub> wake
                 I<sub>32</sub> wake
43
44
                T40 ram
45
                 I40 ram
46
                 T<sub>40</sub> wake
47
                 I40 wake
48
                 T<sub>44</sub> ram
49
                 I44 ram
50
                 T<sub>44</sub> wake
51
                 I<sub>44</sub> wake
52
                 α<sub>1</sub> of ram I<sub>1</sub> (+ = into ram; - = away from ram)
53
                 \alpha_2 of ram I_2 (+ = into ram; - = away from ram)
54
                 a4 of ram I4 (+ = into ram; - = away from ram)
55
                 \alpha_{14} of ram I_{14} (+ = into ram; - = away from ram)
56
                 ale of ram Ile (+ = into ram; - = away from ram)
57
                 a28 of ram I28 (+ = into ram; - = away from ram)
58
                 ago of ram Igo (+ = into ram; - = away from ram)
59
                 a32 of ram 132 (+ = into ram; - = away from ram)
60
                 040 of ram I40 (+ = into ram; - = away from ram)
61
                 \alpha_{44} of ram I_{44} (+ = into ram; - = away from ram)
```

Data Records - MSIV Neutral High Data Base (Cont.)

62	Ratio monitor 4
63	Ratio monitor 5
64	Ratio monitor 6
65	Ratio monitor 7
66	Ratio monitor 8
67	Beam monitor3
68	Beam monitor ₄
69	High Voltage Monitor
70	Vacant
71	Vacant
72	Vacant

APPENDIX I

S3-1 DATA BASE LIST (Sample)

53-1 DATA 345E HOVEMACR 1974 03/02/78

4	•					- 2	3	2+		•	2+	2		**	2+	-2	-	- 1	m 1		- 4	9-9	,	_					-	1	*2	1				-	~			9		•		
CCTAPFOFIL	CE0294/042	0/290	1622	22912	90	CC1067/019	06770	1 167/0	J 22911	0/626	06770	367/62	+21622		GC02297238	1067/02	967/02	CC1367/001	00 / 1 90	167700	CC02297057	r. U.	1622	2.	CC3 22 971 F9	CC12297204	CC0229/205	1290	06770	16770	CC10677019	229/16	1 06 7 / 0	CC0229/058	229/1	1 06	067/0	1167701	10//90	CC05207001	2/01	23	1067/01	LILL BOOK DIL
CCTAPFAFTLE	CC0311/168		112/11	218/10	12	-	1111	15	256/14	226/14	226/14	291/12	21	25	CC2291/125	71792	112/11	1226/14	226/14	276/14	CC0226/149	214/1	CC2 08 0 / 143	\$114	CC0226/148	CC2080/147		226/15	226/15	112/10	661218/123	311/1	218/08	CC0225/001	? ?	112/10	3/13	8/13	-	CC1790/001	226/00	C00226/004	CC 0 226 / 1 5 th	-CT 107700
CCTAPCZETIE	-		CC02271252	1/10	CC0001/197	21.18	1/100	120	001100	001100	DU 1/0	279/00	0076	401/6/2010	CC9277/078	00/100	CC12271767	-	00/	10/10	CC0001/311		735/32	1/30	2	611735130	7/10	107	1/01	5211	CC0 22 7 712 3	001/1	170	CC1289/009	20	12	115	277	2	627567100		CC1289/102		
COTAPE/FILE	200	22775	51/446	1797	2222115	02222715	200	62222115	2222115	44/1	2222115	22/15	2	51/2222	2 0	51/99200	44/20	91/1550	00557/16	00557/18	CC0557/190	61/2500	22/15	57/13	25771	000244/150	1/50/20	0557/19	61/2550	61/250	000557194	22/16	61/25500	761755000	1779	22/16	61/25500	6/25500	02/15500	000000000000000000000000000000000000000	025717	557/20	2	1
COTAPE /FTIF	CC22621185	725271	1197	6672327156	- 146/241	CC3228/383	22813	252/1	24/3	C3232/	28/	1,825874	77.77	2 0	CC3223/419	229271	FC2977/311		C2977/01		CC22527136	0.0297771115	3345/41	-	10722623	063945/420		-	2	2	FC0477/322		~	CC2252/135	2 4	5012765	20111020	C2377702	7/12	621/256200	277702	0/226	1000	r
TTME	0115114	50.00	10107154	1521	1 17 12		-	1 15 12	=	-	21 401	08115142		1513/195		1111	12212	11127153	13312	1 2 4 4 8 4	0 21 155 1 18	1121		14122160	•	12133131	777	49137	101751	. 00	0 3111104	12615	: 22 :	13: 77:21	26 1	11314	154:	1 14 8 4	4 4 4 4 4	18143147	200			
TIME	0.100110	05121151	(9131135	15151111	1331	04137139	FIF	17:01:06	13106154	~	1.30 40	-			16156100	137:3	4810	0190	-	201	21121126	3715	=	6 3	0: 55	11153:20	0 10	11513	2013	22126112	04:42:17		18819	13:03:15	2 :	13911	20 13	21	=	18115:19	22 12 5 14 1			
11.15	6690	211,11.	16476.	. dales	-14246-	11111	48227.	6 1323.	7087	85977.	14662	29743.	2150	54374	3607	18675	17/41.	41274.	44407.	67873	7697	15124.	22646.	30168.	17690.	45212.	61255	677778.	75300.	82822.	119637	34119.	41530.	49042	77673	-1522 K.	220	27	028	47783.	82786	338	44.79	*
114	6141.	11719.	36416.	.5	-12134-	31176.	-	61257.	68415.	311	-12516.	חרכי		2202	1515.	2	~	33158.	46775.	61371.	655.7	11375.	20577.	24119.	350+1.	4.3133.	54206	. 40	3231		16288	1373	33.44.	.61697	6593 1	3180	28203.	333	54243	0 4.46	63742	1944	:	
DATE	11/05/74		11/05/74	11/05/76	-11/02/14-	11/05/74	11/40/74	11/00/14	11/02/74	11/00/76	11/07/75	11/07/76	11/0/1/	11/0//07	11/14/74	11/08/74	11/04/76	-11/04/74	11/03/15	11/98/74	11/08/76		11/03/74	11/09/74	11/00/17	11/09/72					11/10/76			11/19/74		11/11/74	11/11/76	11/11/76	11/11/76	11/11/76				
01.4					*											- 47.	. 66	0	10	101			0					115 *	116 .	117	120	12	121 .	124 •	27	- 1 71 .		135 *		134		141	142	

ST-1 DATA BASE NOVEHBER 1974 OT/DZ/78 COMPLETE) RFVS

		51112	STOP	57497	STOP	MESA	135	HSTATIONS)	MSTVENHIL	ISI	
D. J.C	CATE	£7.4C	TTME	17.45	1142	CC TABELETI E	POTABE/ETIE	CLIANE VETIE	CLTADEZETI E	CLTADE JETLE	4
	11117174	33150.	41 143.	1015514	11129152	CE2477/033	500	LC0227/127	CC 0218/132	36	
	1/12/7	46351	49894	1 4 13 0 150	13134157		02/250	227	213/88	067703	-9
_	11/12/74	4332	5639F.	5 1 3	161	CC2977/135	CC05577208	CC0 22 7 034	218 08	CC3229/066	*
149 *	11/12/74	6135 7.	63597.	1 1 5	17144156	FC2377/076	2125512	227/38	214/09	1290	2+
-	11/13/74	3	7558.	01:39:20	02105157		2/150	22/56	00000	CC 5229/067	5.5
154 *	11/13/74	12314.	15046.	13213	1 10 1	070722660	12550	82/50	90/000	1296	3
v .	11/13/74	20134.	225 24.	41641	1151	FC 1945/414	244/1	126	90	1622	**
	11/13/74	27315.	10022.	51155112	3201	CC2977/041	220547177	CC1735/239	90/080	167/03	**
121	11/11/14	-	37516.	03150131	1251	CC2377/112	000457/178	95/24	0/10	rc1367/036	2
	11/11/76	42430	6 4 9 3 B	11 154:43	1 53 1	CC2377/043	CC2222/170	12	CC2080/065	CC1067/037	- 1
	11/13/74	~	. 5248 F.		1341			10.5/28	080/11	229/11	1
160	11/11/17	57356.	.44165	16134125	1621	CC3 145/41 A	291/442000	136126	8	2291	2-
_	11/13/74	65119	67461.	13139115	7	540/116233	CC0 244/174	922/562 700	0.8	CC# 229/044	2.
_	11/14/74	1+1 A.	3526.	07121137	••	CC32237009	CC22221168	CC1 795/249	CC2 08 0 / 07 1	CC1167/038	-9
165	11/14/74	9 36 8	11114.	07123125	63	CC 3223/087	C22222/171	rc1736/239	CL2060/070	CC1067/039	. 0.
400	11/16//	4 6 5 9 4	18507.	1188140	12120140	CC22527137	5	807797733	90/0	00100100	•
	127 147 1	- 1		-64.74.60	1100111011	1000	222	2 0	3 3	2007000	-
103	11/14/74		2.604	12147137		? ?	12227	101111	200000000000000000000000000000000000000	0407677077	
	11/14/74		45866	2	2	CC12727107	CC0244/164	CC17951745	CC20807076	CC02201175	
1 20	11/15/74		6941	01120136		CC 1228/1193	CC2227178	CC12271108	FC0213/113	CC02297035	. :
177 *	11/15/74		14415			217/576200	000044/165	16/561	CC20A0/109	CC0229 201	
3 5	11/15/74	4642		17857821	132	CC 3223/090	CL2272/160	22	CC0218/093		3.
35	11/15/74		74225.	20131100	1371	CC 1228/09?	562222/192	225/27	CC4327/076	22	
186 .	11/15/74		91707.	72106117	141:	228/0	CC2272/101	CC3225/279	CC4327/078	CC0520/003	3-
	11/14/74	-	10259.	F2117143	151	CC 2252/157	CC2722/183	CC3225/231	CC4327/080	CC0 229/112	2
189 *	11/16/74	15532.	17777.	11102140	04:55:36		002722/184	CC3225/278	CC4327/077	CC0229/117	4
31	11/14/74	30578.	12679.	771E5180	50	CC22571148	561/22273	rc3225/192	CC1243/166	554100	•
33	11/16/74	.45319.	47610	-12138128-	1313	-	2222/1	25/33	CC4 327/115_	CC0229/086_	11
194 *	11/15/74	5331 6.	55176.	512	15117155	CC2252720 8	222271	CC1735/165	CC179n/002	240/290100	1-1
+ 561	11/16/74	604+1.	62542.	712	-	24/11	222211	225/31	CC4 327/116	CC0 22 9/087	
4	11/16/74	67397.	7100A.	15114	14156147	213	1/2226	CC1225/115	CC4 327/114	CC0 229/088	*
200	11/14/74	75 27 2.	77474.	20156112	1311		. CC2222/19n		CC4.327/117	CC0 22 9/0 49	30
000	11/15//4	92378.	54339	73100117	351	CC3223/109	172	CC 1228/114	CC4327/113	060/626033	
201	12/2//		10000	00.6.4.00	01.00.00	-01/02/07/10	000000000000000000000000000000000000000	CC 205 C 20 L	-6.12437103-	- CC 1-104/0-10-10	
100	11/17/74	13775	15876	912216	177	CC22527210	1/24	CC1225/000	CC1243/164	CC1229/091	1
\$ 502	11/17/74	1 1	47343.	1321			2225	FC3225/303	rc4327/102	CC0 229/032	1.7
- 502	11/17/74	4 87 10.	50411.	-	90	CC3228/099	CC2222/196	CC3225/102	CC4327/101	CC0229/130	- +2
* 902	11/11/14	54117.	ro278.	15136116	111	5022527217	1/4720	0017957373		CC0229/253	n
1	11/17/74	.6 787 A	.65746	-17.143.147	1151	-C. 3225/107	222211	CC3225/306	11225	-CC1367/360-	
	11/17/74	71112.	73213.	13145111	12011	CC 1228/106	C22221	CC1225/105	CC 4327/104	CC1 36 77 061	3-
+ 602	11/17/74	78379.	8 76 x 0.	× - F	124	CC3223/108	CC2222/200	611/9/21/00	CC4327/115	CC1 06 7/043	3
211	11/18/74	7115.	9213.	W. 1	2 4 5	CC 1228/117	22227	CC3275/093	CC1243/167	C.110677044	m .
	11/19/74	. 92022	24124.	10710	-	CC3224/116 -	027272720	CC32257121	CC4327/120	10/196	3
	11/10/74	16316.	19034.	10:15:15	1 01 50 134	CC3220/115	6222227199	CC3225/004	CC 0 2 2 6 / 1 5 6	790	54
2	1/13/7	-	~	-12:119:50-	17:54:48	-Ct.3220/11-4	-CG2222/19d-	-CG3225/372-	327/1	-2011067/347-	
218			51400.	16 12 8 1 1 1	17:03:13	5072737113	0022727903	661225/325	CC4 127/124	22071	~ •
	/13/7		63354.	-13132115	19107133	- 6622527218		CC1225/308	- 101/125 700	22	20
. 426	11/11/76	21,212.	76316.	27175151	21:11 144	CC3226/105	501/772000	10 57257511	164777130	201/626600	<u>.</u>

03/02/78	
1974	
NOVEWRER	
UASE	シカニさ
DATA	DAPLE TEN
13-1	Jaku

11	-					1		1			
Mary		3 - 1 -	LING	141		IVECTEI	I = / act	CCIACIA /FI	CLIAPEZFILE	CCIAPETEIL	Y L
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39988, 41°60, 11:03:57 11:23:27 CC1945/424 CC0244/Jn3 CC1705/774 CC2380/152 44772, 48791, -12:54:21 13:37:10 -CG3224/307 GC0557/244 CC1705/775 CC2380/153 54155, 54214, 15:10:10, 15:13:57 CC3946/423 GC0244/Jn4 CC1735/775 CC3380/154 64552, 64676, 17:10:13:1 17:40:135 CC3244/N036 GC0445/243 CC0227/241 CC01112/107	178		37945.	5	1561	02252/14	2115	11/56	00/0	CC1229/155	- 7
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. 54125. 56214, 15102134 15136157 CC39457423 GCD2447304 CC17357726 CC3807154 . 61552, 68636, 17163131 17140135 CC32287036 CC36577243 CC32277261 CC31127107	176	2.	48791.	2	-	32	72725500	28/50	2080/15	CC0228/151-	3+
. 61552. 61546. 17:05151 17:40150 CC13286056 CC04577243 CC02277261 CC01127107	174	.5.	56214.	0	3	366	(199200)	3	2180/15	CC0229/210	•
100000000000000000000000000000000000000	12:	. 5 .	63636.	17167171	17:40:35	3228	E	1163	0112/1	190/196100	+ 5
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1						200	,				

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COMPLETED REVE	NSE MOVEMBER 197	212
	IF AT	נמ נש

	1011	9013	16113	9010	504	100	Mery (Tores	HWINLOW	107	
DEV	1145	47.1	1440	TAG	CT TAPE/FTIF	G CTASE/FILE	CCCAPE / ETIF	CCTAPE /FILE	CCTAPEZET:	KP
1	4117	2779	0112011		CC3224/008	. 5	FC1705/128	CC2380/156	CC0229/220	
11/24/1	-	14306.	62127133	n 315n 125		. 0	6217367133	2969/0	CC3229/061	
2726111 . 200		21718.	05127111	0 6:01:57	Cr22521126	2005571747	rc1735/139	CC2380/011	5072297062	2
1 . 5		20120.	07134143	171717		5727255000	CC17367103	CC2089/014	CC02297053	,
	4233	.956.4	11145103	12:12:35	CC 7228/174	5005577139	CC3 22 7 / 118	CC 0216/123	9/0.0	-2+
		51369.	17141122	14115119	CF 7228/133	C.0557/19A	CC1 795/187	CC2069/013	CC0 2297010	*
• •		58784.	15844874	16:19:40	CC 1725/137	CC0 544/191	60175257	CC4 327/127	CC 322 97 011	4 :
		775.05	17143125	19123112	CC 1229/121	0.025/1240	CC1222E/20E	F. 4. 52 7 10 4 E	CC05207011	; ;
301 - 11/25/74	78381	81017	21161113	221 20 142	CC1224/126	121/165000	CC1225/21	CC4 127/1184	CC05217011	; ;
		9433	02102115	02137112	CC2751/760	CU0557/120	CC1 795/191	CC2 04 0/012	CC32297013	, M
11/20/14	-	16856.	0417193	04141155	0022527159	CC0557/119	561/56/135	CC2080/015	CC0229/256	
414 * 11/26/74		39179.	10115173	10151118	602757/149	05011250	CC1795/134	CC.208n/015	CC0 229/156	2+
116c/11 + 60r		46480.	12124152	12154179	51765625	6505577122	660777093	CC0218/098	CC0229/019	+ +
410 . 11/26/74		53442.	14123113	14158101	CL1252/152	020557/124	CD-227/007	CC0218/004	CC022970+0	;
		61294.	16126133	17:01:27	0022527151	CC05571123	CC0 22 77 09 4	CC0213/102	000 2297 046	+
1	66.35	F3784	13834113	19184143	51/8262	F50557/251	00175757100	CC1243/174	CC05207013	+, ;
313 * 11/25/74	_	76086.	20131122	21108115	003723/149	2527755000	0013255730	CC 327/188	CC05207014	• •
1121114	2		*0107100	01:14:47	555557151	CC055 247175	CC1 735 11 85	CC2 ab 67617	0507677070	· .
11/2/14		19691.	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	02:22:00	141/36/35/3	CC3716000	07/106/170	CC20807070	CC0220157	, ,
171 - 11/2/17	19470			121.21.11		001/24 2010	FC1275/201	CC 427/090	510/025000	
		404	17 19 19 19 2	55472424	CC1224/128	CC0557/182	262752233	CC4327/091	CE35207016	2.
2		56297	1510118	1 41 14 116	CC 122 a/ 127	020557/193	CC3225/203	CC4 327/092	CC05200017	2
3 + 1		4369A.	17112147	17141137	2447246533	CC0244/178	36126	Cr2089/0.4	CC0229/158	2
2 . 1	. 76414.	79501.	2111115	21146120	63232115	CC0244/101	021/120	FC0213/125	CC02291242	- 4
1		8530Z.	23116133	23151141	FC3232/163	CC0 244/182	CC0 227/115	CC0218/120	CC32297255	-
1 . 1		. 7969	01120120	01155103	00 3945/441	CC0244/305	150/502 100	0020001082	CC0 229/159	2
		14806.	-03123142	33158125	CC3232/162	DC0244/134	CC0 227/112	CC0219/117	CC 0 22 97 248	- 2
		21705.	46141150	06:01:45	CC3232/161	621/552000	500277/111	CC0718/116	CC0 2297243	٠,
		. 36662	51101120	2884886		900/442000	22/46/10	111/10007111	\$17622000	:, .
311 - 11/28/74	56572	2042	15112113	1611713	CC 2761/416	101/44/000	65/56/10	CC2000130	GC02297150	- 0
	64330	66049.	17147113	1 2120148	CC2761/426	CC0244/328	2627367235	CC2360/113	CC0229/176	1-
1-1	1	.77448.	-10143119-	20123100	CC27511425	-CU0244/011-	- 001 70 5/331	CC2080/159	CC0229/179	
		A1851.	21 152133	22127110	602761/424	000244/110	621/36/100	CC2000/157	CC1229/213	<u>.</u>
1		21934.	06105143	36139157		CC0244/113	rc1795/294	CC2060/112	CC0 229/178	•
		11345.	7216 11 8 11	10 8 6 4 8 9 6		411/44/000	467467100	CC2060/114	22622000	
344 11/24/14		40154	12:18:57	16169171	6177777	CC222217	50072250	CC 0218/101	640762000	
	1	E0348	16121117	1 615514	62252121	022222716	CC0227/105	C21218/100	CC0229/116	
7 . 1	6623	68749	18174170	1085841	5532377160	000244/173	000277121	CC0214/125	CC02297251	0
	1	75732.	27127131	211171111	6627611429	CC0244/315	rc1795/132	CC2 08 9 / 15 0	CC3 229/215	0
1 . 1	610.	A 1127.	72130141	23115121	CC7252/149	CC12447116	128/56/100	CC2089/151	0092237218	0
	202	4132.	73133145	711108121	0027617420	CC0244/171	926/564 103	CC2080/087	0 22	0
	3947	41006.	10157151	11121175	007257/214	001547/117	50072 22 1700	CC0219/011	150752600	5 6
-	1264 -	44346	12151 143	13156125	CC22527212	C.C. 118	- C	10/01/01/01/01/01/01/01/01/01/01/01/01/0	201000000	
		45767		15:29:26	002757/160	GC15577239	401/30/13	500000000000000000000000000000000000000	500 16 22 16 10	> c
159 * 11/11/16	6 1451	70524	14100150	19:35:27	CC2257/144	C0557/114	10175257	2 0	CC3 22970 72	00
		5			1					

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ST-1 DATA GASE DECEMBER 1974 03/07/78 COMPLETEN 25/5

-		STANT	STOP	STARE	STOP	A25.	105	MSIVCIONS	CHEDAISE	HSI	-
150	DATE	1145	3-11	TIME	7 146	CCTAPC/FILE	-	d	CCTAPE/FILE	CCTAPE/FILE	4
* 272	12/01/74	11575.	17557.	1112		52	0222277	•	21	GC0229/037	•0
364 .	12/01/74	18956.	21033.	515115	15150172	C-22527391		CU1795/257	CC20807048	4507622033	•0
166 .	12/31/74	25117.	28414.	67118155	17153111	CC2257/094	CC0557/151	15/30	CC0112/129	000 2297 055	•
* 932	12/01/74	33717.	36794.	113	•	CC2257/19A	CC0557/149	12/502	(C2000/145	CC0229/073	-
u	12/01/74	4113	47176	-11124157	-11153134	-622557137		CC1 775 / 003	CC20607020-	CC0229/074	
. 892	12/01/74	2 4 . 4	e1666.	121	14102135	66725263	00557730	7 00 / 5 1 2 1 3 3	CC2060/023	rc0229/077	-
* 691	12/01/74	5635	67976.	5:3	10513	61345143	2054472	CC32271284	~	CC0229/195	-2
376 .	12/12/74	21115.	25130.	45165150	1221	0717585770	0	CC1227/279	CF0112/125	CC0229/235	3-
* 222	12/12/121	28427.	35502	3	12182161	911	001777200	CC3227/153		CC0229/236	3-
340 .	12/02/74	50545.	52517.	14102121	1 36	•	27/00	79	CC0219/159	CC0229/078	\$
TA2 +	12/02/174	65450	67360	13110100	18162139	- 0072557101	CC2222/460	701/56/100		-CC1229/080-	
* 742	17/02/74	.6.60.8	A2107.	2211 1123	1491	0039457436	000244/210	CC1775/316	022080/144	000229/196	+2
	12/192/74	23030.	25169.	16145190	5312	CC2257100	CC22227461	6007567100	CC1790/016-	CC02297075	*~
3.9 .	12/13/74	30.59.	325 10.	08127138	19210	t	0022227436	3/1	CC0196/035	CC0 229/224	*
+ 061	12/31/74	37.82 11.	33891.	10:30:13	10415	377/576L 3	6522227435	116	CC0196/093	000 2297 226	
331	12/01/24	45454.	47253.	12144117	-	6	0004577306	CC1227/177	C00218/142	CC1229/122	÷.
n (12/03/76	52342.	54614.	14185141		3345/233	CC0557/008	-416/56/133-	CC1790/021	-0207625070-	
365	12/01/14	59313	61975.	16139122	17112154	C 1945/234	CC15577389	CC17357311	rc1799/018	CC02297021	
376	12/01/2	6/254.	. 693 Sh.	1414111	19115145	622527165	211/255000	911 /56/100	5520807134	5507525075	
4 961	12/13//4	61117	97.000	25. 27. 66	27.20.57	500000000000000000000000000000000000000	C.C.C.C.C.114	1.566713	CC20807153	10076CA15CA	• •
. 00	12/0/21	25172	27404	06.67.64	270 12 12 0	326/37623	P. 0.5 E 7.0 4 4	0.0736700	C + 20 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	100102000	
416	12/05/74	56105	58376	15:18:24	2	0 -	CC2227/308	CC1 795/300	CC2 08 0/124	CC02297202	200
.18 .	12/95/74	7937 4.	73941.	13142153	20117120	. ~	000557/316	CC1 735/018	CC1790/025	rc0229/026	, M:
+ 524	12/06/74	21336.	21371.	05153103	SF129172	027617950	0095577117	0201261 100	CC1790/027	CC0 229/127	-1
457 .	12/06/74	50371.	52760.	14134152	14133119		0207577320	CC1795/023	CC1790/039	CC1229/129	+
+ 624	12/04/74	65347.	67454.	916018	13144111		0.005577321	4207567100	CC1790/031	CC0 229/130	÷ 5
. 11	12/02/24	406	8-148.	22114133	20169166		6627227459	CC1 735/071	CC1790/028	CC1 22 97131	-
	-12/01/24-	618	12297	115111	93123126	496/192200	Cru2577847	CC1735/258		CC.02297132	2.
432	12/07/74	23025.	250 A 9.	16127115	06158108	CC2761/163	CC0557/148	261 795 7026	CC1700/033	CC02297139	- 2
	12/0//4	57514.	. 49764	11153111	111107157	CC70.677.5	CC2222723	CC1 795 701	CC20807025	CC02297481	
* 277	12/17/74	81732	81766	22 141 141		3165/245	CC2227510	1017367100	CC20000131	CC0229/140	
. 574	12/08/74	3970.	12034.	10:	02120173	3945/244	CC22221502	012/202150	CC2060/117	CC3 22 97 190	. ~
4-154	12/48/74	. 6 141 9.	-56043-	-14159119	-15134102	-	GG22227591	C011951202	CC2 08 0/ 120	CC0229/2*0	-3+-
* 155	12/00/21	11544.	13635.	03112123	7194	0	0-22221515	601/562100	CC2 UB 07177	6617622000	2
. 654	12/03/74	26134.	28256.	07116117	37:50:55	σ.	6077227516	CC1705/310	CC2 06 0/1 18	CC02297190	
. 297	12/00/76	. C.		111701117	11.03.11	C 2 44 5 / 4 5	000000000000000000000000000000000000000	21,196,179	1111000000	CC0229/183	
470	12/11/74	21112	22301	05171	06613610	- 0	51675555.J	CC0279/151	C.0196/055	CC1229/162	
4 14	12/101/21	27347	29705.	07139106	11511	3345/411	0022221334	273/15	60156/056	CC1229/163	
. 215	17/10/74	34351.	17019.	03142110	11615	•	CC22227501	5027367130	rc2080/121	CC 0 22 9/ 27 2	* 2
* 727	12/10/74	~	51647.	7	••	0	45(1156000	0.07567100	CC1790/037	FC0 229/134	*
. 525	12/10/74	56333.	54961.	15145122	:22	FU3232/004	22/30	2/5	F.2080/118	CC1 22 9/184	- 5
476 4	12/11/74	-	46775.	53	1541	C.	55557:9	CC1795/291	7	CC0 229/195	m. 1
	12/10/76	71571.	. 6889.	112311	1 32 1	3945	1250	21/0/2	CC01967051	CC 22971 35	٠, ٠
	12/11/76			40:4512	22183121	Cr 32327 002	215/22/200	KIN /5E/177	CC17907135	CC0229/146	- 1
482	12/11/75	123		66.19.35		6767575	1/200	C. 1 73 E / 0 7 2		CC02207136	. :
. 983	12/11/74	4 4		1016101		900/21/20	CC 1244/213	CC0227/148	18/15	000 22 97 22 9	
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